

AMENDMENTS TO THE SPECIFICATION

Please amend Page 8, lines 1-10 as follows:

R, In order to move the unloading auger into its unloading position U, the second segment is first rotated rearward about the hinge 46 so that the axes of the first 41 and second 42 segments are coaxial. An actuator 21 (~~not shown~~) is provided along the outside of hinge 46 and is connected to both the first 41 and second 42 segments. The actuator 21 provides the force necessary to rotate the second segment 42 from its storage position S to its coaxial position. In the preferred embodiment, the actuator 21 includes a hydraulic cylinder which can be remotely operated from the operator's station 16. Other variations, however, may include electro-mechanical actuators or may include manually operated mechanical mechanisms.